Ice-Capable Seagliders: Extended Under-Ice Operations and Real-Time Acoustic Navigation

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Seagliders
 Baffin Bay – Davis Strait
 MIZ Program
 Perspectives



Long Endurance Autonomous Seagliders





Missions include: eastern and western boundary currents (Kuroshio), typhoons, quantitative biogeochemistry, fronts, eddies, submesoscale dynamics, subpolar, Arctic and Antarctic

- 50 kg, 2-m length
- Cycle 0-1000 m, ~6 km ~6 hours
- Horizontal velocity ~0.25 m/s (20 km/day)
- Vertical velocity ~0.1 m/s
- Typical deployment 3-5 months, longest to-date ~11 months.
- Endurance depends on • ambient stratification, dive depth and desired speed.
- 2-way Iridium comms, data upload, slow remote control
- Temperature, salinity, pressure, current, optics, dissolved oxygen, turbulence, depth-average velocity (inferred).





Long-Endurance Seagliders for Ice-Covered Oceans





• Enhanced endurance, reliability

Lee, Rainville, Gobat (APL-UW)

- Compass calibration/check procedures for high-latitudes ops
- Real-time acoustic navigation
- Ice detection- ice climatology, temperature, altimeter
- Enhanced autonomy with 'ice 'behaviors'
- Routine operations in full ice cover and marginal ice zone
- Acoustic communication for data transfer

Broad Access

- Remote regions, full ice cover
- Ice-ocean interface, marginal ice zone.
- Persistent sampling- long endurance

• Risk Mitigation

- Limited exposure to ice-ocean interface.
- Data return when open water available.
- Highly Adaptable
 - -Simple logistics.
 - Real time reprogramming.
 - Flexible sampling.
 - Scalable.



Acoustic Geopositioning & Communication for Autonomous Platforms

Additional information & community report: http://anchor.apl.washington.edu





Davis Strait Arctic Gateway: 780 Hz Narrowband **Real Time Acoustic Navigation**

- Multilaterate from fixed sources (bottom moored) Broadcasts on known schedules r = 60.1 km, e = 0.9 km 26.9 km, e = 0.1 km Platforms carry accurate clocks, sync when possible 59.3 km, e = -0.2 km 42.8 km = 1.8 knFraction Good Receptions (Correlation Crit Correlation vs. Distance 0.9 0.6 Fraction with Corr > 0.2/0.3 Open water mear 0.8 Correlation ^{6.0} ^{6.0} ^{7.0} ^{6.0} 0.7 0.6 0.5 Similar correlation, but range 0.1 errors large when ice is present 0.4 50 100 200 150 Distance (km) Ice cover, surface ducting 0.3 greatly reduces range of 0.2 Open water mid-freq O(1 kHz) signals • Higher correlation 0.1 required for RT fix Ice covered when ice present. 20 40 60 80 100 120 140 160 180 200 Distance (km)
 - Accuracy ~1-2 km.



Year-Round Operations in Davis Strait

Lee, Gobat, Shilling, Huxtable (APL-UW)



SG108, SG183 & SG141

9 Jun 2010 – 17 Jun 2011 Jan-May: ice-covered Jun: transition Jul-Nov: ice-free Dec: transition

- 34 sections
- 2113 profiles
- 1762 w/ ice autonomy
- 84% correct detection
 - 11% ice-obstacle
 - 42% ice-temperature
 - 47% open water
- 2.5% detect errors
- 13.5% ambiguous
- 52 forced surfacings
 23% success





Autonomous Investigation of the MIZ



Craig Lee (APL-UW), Lee Freitag (WHOI), Martin Doble (LOV), Wieslaw Maslowski (NPS), Tim Stanton (NPS), Jim Thomson (APL-UW), Mary-Louise Timmermans (Yale), Jeremy Wilkinson (BAS) and the MIZ Team



Ice Mass Balance Buoys- Wilkinson (BAS), Hwang (SAMS), Maksym (WHOI), Richter-Menge (CRREL)

Wave Buoys- Wadhams (Cambridge), Doble (LOV)

Surface Wave Measurements- Thomson (APL-UW)

Autonomous Ocean Flux Buoys- Stanton, Shaw (NPS)

Autonomous Gliders- Lee, Rainville, Gobat (APL-UW)

Biogechemical Measurements (Perry, U. Maine)

Acoustic Navigation and Wavegliders- Freitag (WHOI)

Profiling Floats- Owens, Jayne (WHOI)

Ice-Tethered Profilers- Toole, Krishfield, Cole, Thwaites (WHOI), Timmermans (Yale)

Remote Sensing- Graber (CSTARS, U. Miami), Hwang (SAMS)

MIZMAS model- Zhang, Schweiger, Steel (APL-UW)

Regional Arctic Climate System Model- Maslowski, Roberts, Cassano, Hughes (NPS)

Arctic Nowcast/Forecast Model- Posey, Allard, Brozena, Gardner (NRL)

Melt Ponds, Biology, Biogeochemistry- Kang, Yang & colleagues (Korean Polar Research Institute)

External Collaborations- NRL, NASA, NOAA, ESA

- Tightly integrated program.
- Interdependent elements.
- Exceptional collaboration.
- Strong team effort.



Models Struggle to Reproduce Dramatic Reduction in Summertime Sea Ice Extent





- 7 million km² in the 1970s
- 3.4 million km² in 2012
- Wintertime sea ice maximum declining.
- Decline primarily thermodynamic, other processes may increase in importance.

Minimum Sea Ice Extent



median



Improve Predictability – Refine Models

- **Process-level** investigations
- Improve physics, parameterizations
- Continued testing against sustained • observations

Refine physics <u>at the ice edge</u> – between pack ice and open water – <u>Marginal Ice Zone</u>





<u>Science</u>

- 1. Understand the physics that control sea ice breakup and melt in and around the ice edge (Marginal Ice Zone MIZ).
- 2. Characterize changes in physics associated with decreasing ice/increasing open water.
- 3. Explore feedbacks in the ice-ocean-atmosphere system that might increase/decrease the speed of sea ice decline.
- 4. Collect a benchmark dataset for refining and testing models.

<u>Technical</u>

- 1. Develop and demonstrate new robotic networks for collecting observations in, under and around sea ice.
- 2. Improve interpretation of satellite imagery.
- 3. Improve numerical models to enhance seasonal forecast capability.

Z Atmosphere-Ice-Ocean Interaction







Challenges



To understand the processes that govern sea ice melt:

- Ice mass balance.
- Sea ice dynamics (locally and regionally).
- Open water fraction/floe size distribution.
- Surface wave penetration and dissipation.
- Meteorological forcing.
- Upper ocean variability.
- 1. Resolution: Resolve temporal evolution and small-scale spatial variability (4-D physics).
- 2. Persistence: Sample entire melt season (Jun Sep). Physics change as a function of open water extent.
- **3**. Access: Measurements in full- and partial- ice cover.
- 4. Scalability: Large number of platforms provide distributed sampling, mitigate risk.



The Revolution in Robotic Observing







Putting the Pieces Together





Fast and light logistics Ice-based array deployed by aircraft in April (full ice cover). Drifters & gliders deployed in July, with first open water. Array drifts with ice pack Extensive remote

sensing (SAR): open water fraction, floe size distribution



Broadband Acoustic Navigation

Freitag (WHOI), Gobat, Webster, Lee (APL-UW)



Buoys:

- Transmit every 4 hours, fixed times.
- GPS synched.
- 900 Hz carrier.
 - ~1 bps data rate.

Receiver on Glider:

- Measures time, computes range.
- Decodes location of buoy.
- Ranges and source locations used to compute real-time position.

Mobile Acoustic Sources

- Ice-based nav sources <u>drift</u>.
- Therefore <u>must transmit source</u> <u>positions</u> to allow real-time geolocation by gliders.
- Data transmission capability also means <u>commands can be sent to</u> <u>glider</u>.
- May also be used in moored (fixed) configurations.

Glider Receiver Board

Glider Receiver Hydrophone





Z Beaufort Sound Channel Yields 400+ km Range

Freitag (WHOI), Gobat, Webster, Lee (APL-UW),



Measured Temperature Profile 0 Cold Mixed Layer "Warm" Alaska **Coastal and Summer** -100 Sound **Bering Sea Water** Channel **Cold middle layer (Winter Bering Sea Water)** -200 Ξ Atlantic depth -300 Water Depth (m) -400 epth -500 **Transmission Loss** Range -600 -700 -800└─ -2 -1.5 0.5 -0.5 -1 0 Temperature (Deg. C)

Glider Receptions vs. Depth



Glider performance: To 100 km at all depths. To 400 km when in duct.



MIZ Autonomous Sampling (1 Mar – 20 Oct 2014, 8 months)







Glider sections across the MIZ





In September...

- Deeper mixed layer.
- Strong lateral variability.
- Thickening of PSW layer.







Glider sections across the MIZ





In September...

- Less light.
- Weaker Chl max.
- Large Chl signal in the mixed layer.











All Gliders: 15 August - 1 September (ice edge retreat)





Results



https://www.elementascience.org/collections/special/special-feature-marginal-ice-zone-processes-in-the-summertime-arctic/ http://www.apl.washington.edu/project/project.php?id=miz

<u>Science</u>

- 1. In this year, waves do not appear to have played a large role in breakup of the pack- thermodynamics dominate.
- 2. Surface waves attenuate rapidly upon encountering ice, even in fractional cover.
- 3. Signatures of lateral mixing and vertical exchange driven by small-scale front and eddies near the ice 'edge'.
- 4. Clear contrasts in chlorophyll distribution associated with ice 'edge'. <u>Technical</u>
- 1. Autonomous observing from pack ice, though the MIZ and into open water spanning an entire melt season (March October 2014).
- 2. Under-ice glider operations using new, drifting broadband sources.
- 3. Acoustic receptions at 400+ km due to shallow sound channel associated with Beaufort Sea near-surface temperature maximum.

Some Thoughts on the First 20 Years

- Struggling with scalability- ease of use, reliability, cost, science focus...
- Gliders well-tuned for sustained sampling of regions with strong gradients (mesoscale/submesoscale process studies, fronts, boundary currents).
- Glider and float cost per profile similar (\$20k/200 profiles, \$100k/1000 profiles)- usage differs. Floats- distributed, Gliders- concentrated.
- Sustained long-term efforts typically reach beyond basic research to serve other needs- operations, local communities...
- Local logistics critical for sustained observing efforts.
- Practical considerations (e.g. EEZ access, hazmat shipping) can play controlling roles.

Gliders are one tool in a large toolbox. Creative, multi-platform approaches offer great power. Focus on the science questions and consider the full system.



Glider sections across the MIZ





In September...

- Relatively cooler, saltier mixed layer in open water.
- Thickening of PSW layer.
- Weaker halocline stratification.







MIZ Remote Sensing





Experiment planning, execution and analysis.

TerraSAR-X (418 images)

Radarsat-2 (69 images)

> 675 SAR collections (plus 464 additional as needed)

Dedicated support from National Ice Center, meteorological reports & drift forecasts inform planning & targeting.

Agile targeting to follow drifting instruments, respond to rapidly-evolving MIZ

Targeting strategy and protocols developed & tested prior to main program. Small targeting team (remote sensing, models, observations) led by Bill Shaw



'Fast & Light' Ice Camp Logistics



- 60+ assets deployed over • 300 km km range.
- 2 Twin Otters + 1 Bell 412 •
- 1 week setup, 1 week ops

Personnel = 6 persons + dog

- 3 x scientists/engineers
- NASAJESA validation line 3 x helicopter personnel

Accommodation tents

Automatic weather station

Wave Buoy

buoys

Ice mass balance

Helicopter site: fuel + equipment



Autonómous flux buoy

Ice tethered profiler

Kitchen tent

Twin Otter Runway



'Fast & Light' Vessel Logistics



R/V Ukpik, July 2014



Deploy: 4 seagliders 3 SWIFT buoys 2 wavegliders



Ice edge measurements (turbulence wave attenuation)

R/V Norseman II, Sept 2014



Recover: 4 seagliders 3 SWIFT buoys 1 wavegliders

Ice edge measurements (CTD and wave attenuation)





- Ice-Tethered Profilers at C2 and C4
- 70-250 m depth
- IW energy increases from spring into summer
- IW energy appears to increase with increasing open water fraction.





Cannot directly measure ice thickness from space **Need autonomous platforms**







Open water fraction





- Complex algorithms needed to separate floes.
- Not fully automated
- Floe size distribution
- Fraction of open water







Wave measurements





Under the ice

On the ice

In open water (and ice)



Nortek AWAC at 50 m sub-surface

WHOI BGEP mooring "A" 75 N, 150 W



Wave buoys (drifting)



SWIFT buoys (drifting)



waveglider (piloted)



Surface Wave Attenuation in Sea Ice

Thomson (APL-UW)







Surface Wave Attenuation in Sea Ice

Doble (LOV), Thomson (APL-UW)







Wave Buoy high ice conc.



 Waves strongly modulated by even small concentrations of sea ice.

- Waves in sea ice only after early September, when there is significant open water south.
- Episodic wave events, but seen at multiple sites.



Real Time Situational Awareness







\Downarrow Extent + \Downarrow Thickness = \Downarrow sea ice volume

Quantity and quality of sea ice impact processes and feedbacks.



Mixed Layer Contrasts



15 Aug –01 Sep 2014 (ice retreat)

15 Sep – 01 Oct 2014 (ice advance)



- Open water: Warm/fresh (melt + solar warming + PSW entrainment)
- Ice covered: Cold/salty, deeper MLD
- Open water, ice edge largest lateral variability



- Open water: Warm/salty (melt + solar warming + PSW entrainment)
- Ice covered: Cold/fresh, deeper MLD
- Lateral variability further into ice





1990



Rog. SSM/I | Ice Concentration (%) | 20120601





140°W



June

IZ

August

SSM/I - Posey





Pack Ice **Open Water** Marginal Ice Zone



The 2014 Beaufort MIZ



Beaufort Sea MIZ, August 2014



Fram Strait MIZ



Sea ice dynamics



Regional: Satellites are the key Local: GPS is the key

May 8



- Understanding ice dynamics leads to a better Ο knowledge of ice deformation processes.
- Need information on local and regional level 0

Micro-temperature Seaglider

Luc Rainville and Craig Lee



Extended (many months) dissipation measurements from autonomous platforms.

Fully integrated system.

- Does not affect flight and endurance.
- Real-time data processing and transmission of turbulence profile after each dive.
- Data quality comparable to free-falling systems.

Successful 1-month deployment, 6-month deployments in-progress (SPURS- 3 gliders).

