#### **AUVs for Under-Ice Studies**

Hanumant Singh, Northeastern/ WHOI Ted Maksym, WHOI Guy Williams, U Tasmania Jeremy Wilkinson, BAS

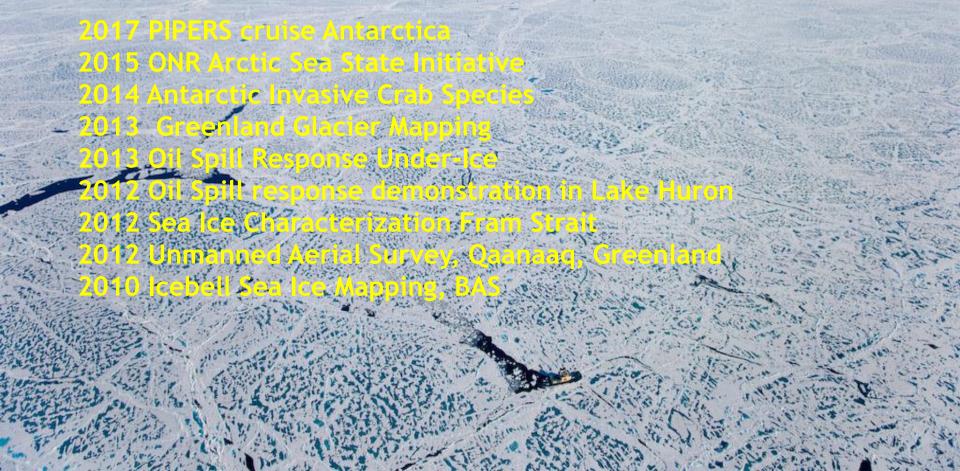
and a large supporting cast



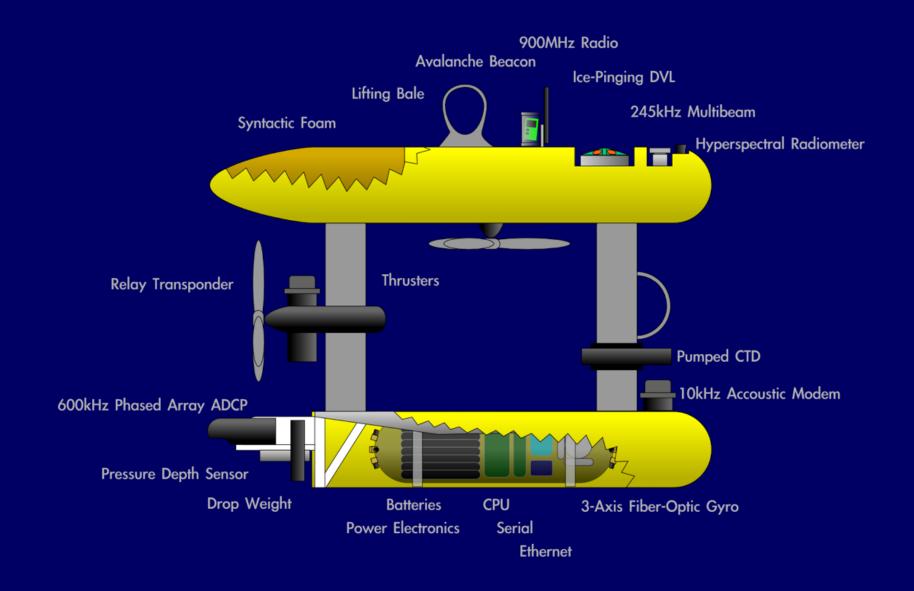
# 2007 Gakkel Ridge Expedition

<u>Science</u>: To study the geological, chemical, and biological characteristics of hydrothermal venting on the Gakkel Ridge.

Engineering: To develop new technologies to enable deep-sea research in ice covered oceans.



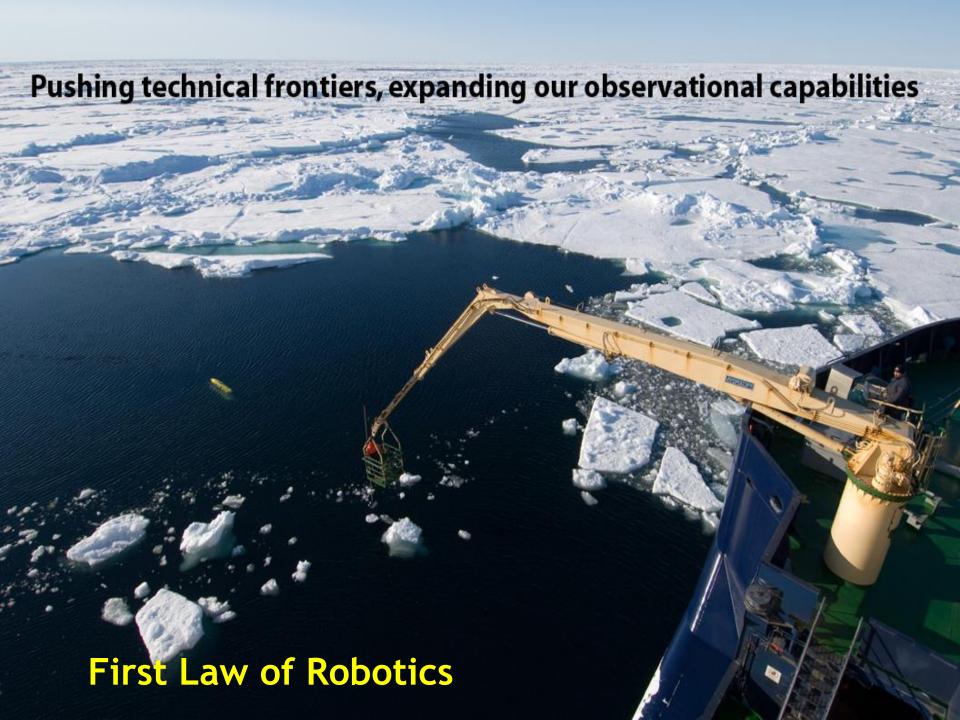
### The Jaguar AUV



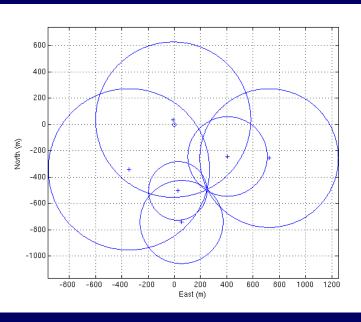
# **AUV Navigation**

#### **Issues: Good and Not so Good**





## **Second Law of Robotics**



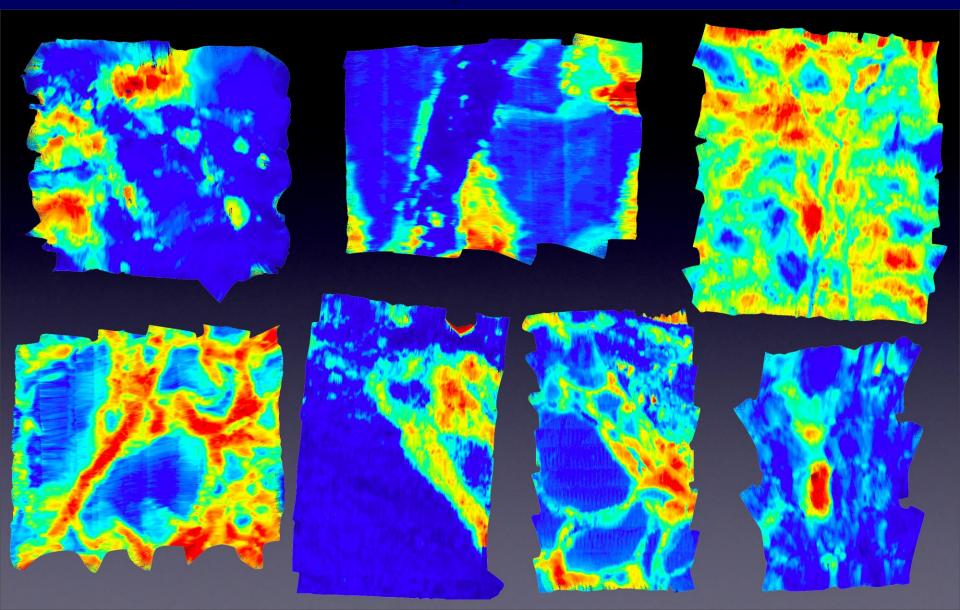


#### 2010 The IceBell Antarctic Experiment





# Multibeam Mapping using SLAM (10cm res, 500mx500m)

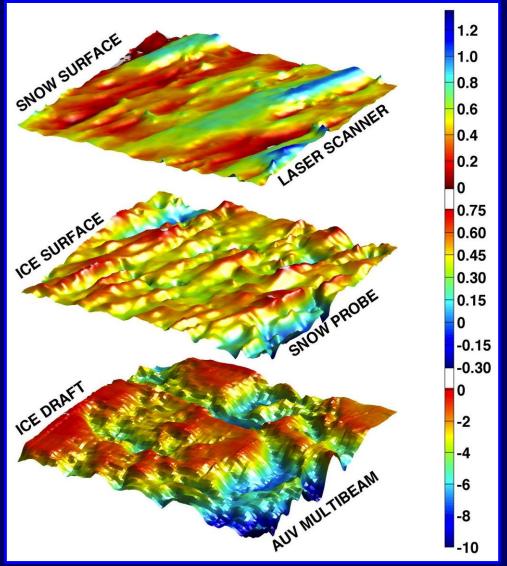


# Otter Overflight Mosaic



#### 2012 Sipex II Expedition with AAD

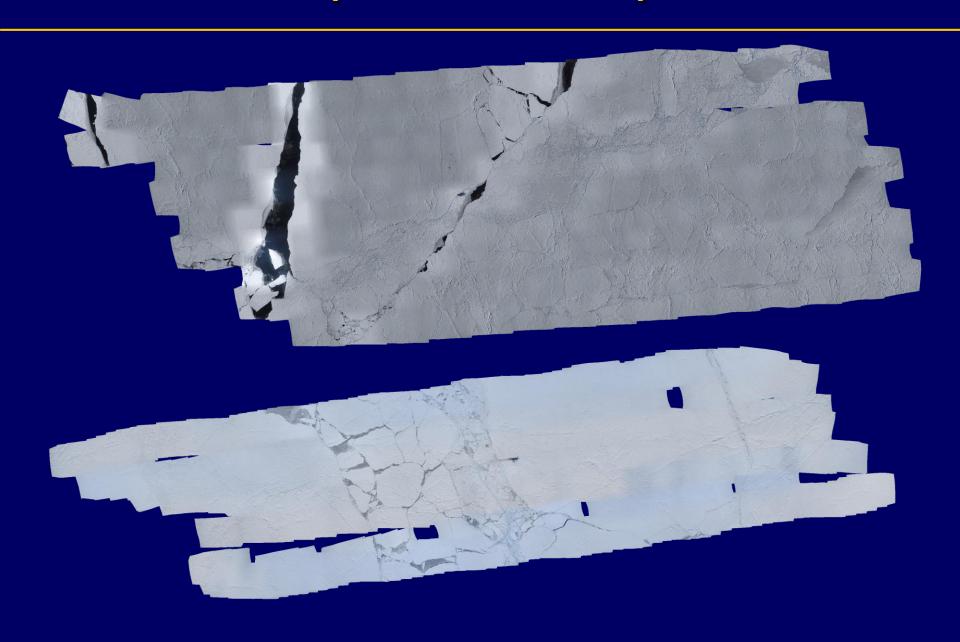




# **Mapping with Drones**



# R/V Lance (Wilkinson et al)



#### What's the Future?

Spatial Coverage (100m – 1000km) **Temporal Coverage (Hours – Years)** Sensor Resolution (cm – km) Platform Navigation (cm - km) **Manipulation and Sampling** (sessile/motile) Size, Expense, Risk Tolerance etc **Hybridization** 

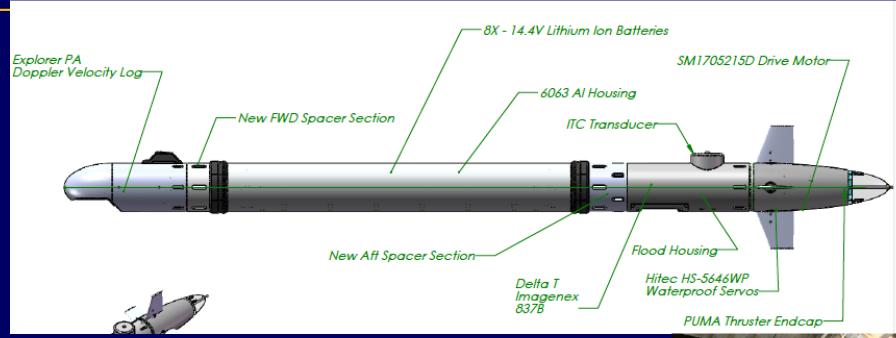
# **ASVs**







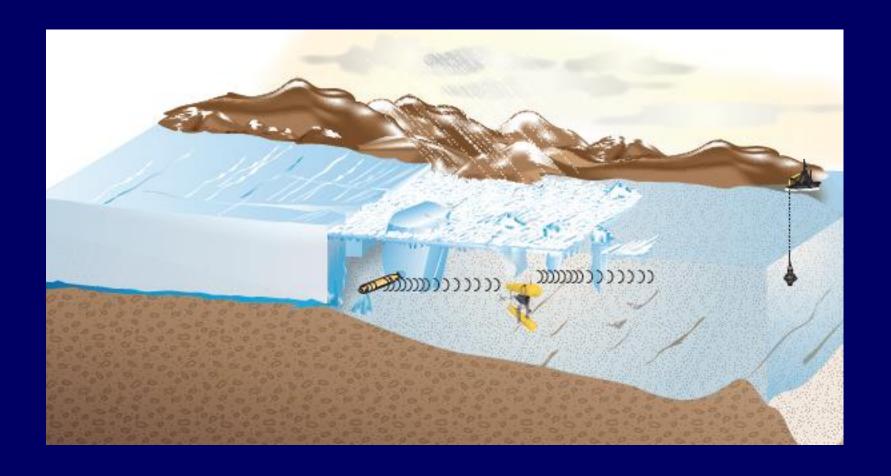
### Where are we going – Seabed 125



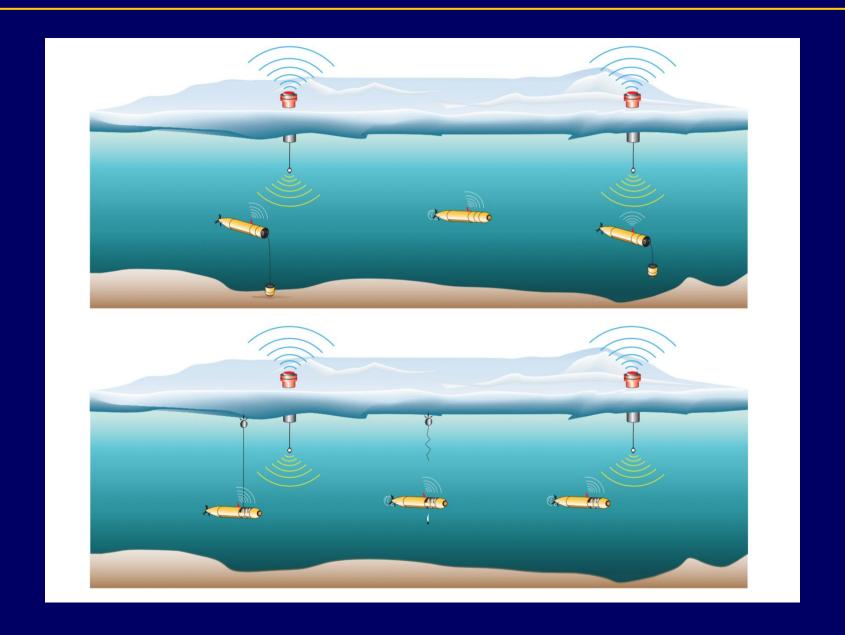
Cost per bit of informaton Reliability Simplicity (can a sea –ice person operate it)



# **Multi-vehicle Deployments (Autonomy?)**



# **Over-Wintering AUV**



#### Acknowledgements



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